Analysis of Youden square design with two missing observations belonging to the different rows, different columns, different treatments (Not common in both the rows)

Dr. AK Kaushik and Dr. Shiv Kumar

Abstract
Two missing observations can occur in a Youden Square Design in eight mutually exclusive ways. In the present study, the authors have tried to discuss the case of two missing observations belonging to different rows, different columns, and different treatments (both do not belong to the common set of treatments in both the rows). Estimates of the missing observations and variances of the various elementary treatment contrasts have been obtained by using Bartlett’s covariate analysis.

Keywords: Average variance, adjusted treatment total, Bartlett’s covariate analysis, bias

1. Introduction
In a Youden Square Design, \( n = vr \) experimental units are arranged in \( v \) rows, \( r \) columns and \( v \)-treatments are allocated at random to these experimental units subject to the condition that each treatment occurs once in each column and each pair of treatments occurs together in \( \lambda \) rows. A necessary and sufficient condition for this is that a B. I. B. Design with parameters \( v, b = v, r, k = r, \) and \( \lambda \) exist.


2. Material and Methods
This includes two sections. In section 1, the covariate analysis with two concomitant variables is presented in brief. The detailed covariate analysis pertaining to the present discussion has been discussed by Kaushik A. K. and Ram Kishan (2011) \(^12\). The subject matter discussed in this section is not entirely new but its presentation is new. It provides the relevant information and forms the basis of the present study. Section 2 deals with the subject matter under study. The expressions of estimating missing observations, various sum of squares, and their effects are explicitly defined. The whole procedure is illustrated with the help of an example.

Section 1
Covariate Analysis: The ANCOVA Model with two concomitant variables \( X_1 \) and \( X_2 \) is given below

\[
Y_u = \mu + \gamma_k + \delta_i + \cdots + \rho_m + t_1 + X_1u\beta_1 + X_2u\beta_2 + e_u
\]  
(2.1a)

Its corresponding matrix model is

\[
Y = Z\pi + At + X_1\beta_1 + X_2\beta_2 + e
\]  
(2.1b)
with usual standard notations. The error sum of square will be

\[ \text{E.S.S.} = \text{min. of } (Y - Z\pi - At - X_1\beta_1 - X_2\beta_2)' (Y - Z\pi - At - X_1\beta_1 - X_2\beta_2) \]  

(2.2)

with respect to \( \pi, t, \beta_1, \) and \( \beta_2 \) only. We get the least square estimates as below:

\[ \hat{\pi} = (Z'Z)^{-1}(Z'Y - Z'At - Z'X_1\hat{\beta}_1 - Z'X_2\hat{\beta}_2) \]  

(2.3)

\[ \hat{t} = \hat{c}(Q_{(y)} - Q_{(x_1)}\hat{\beta}_1 - Q_{(x_2)}\hat{\beta}_2) \]  

(2.4)

\[ \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \end{bmatrix} = \begin{bmatrix} E_{x_1x_1} & E_{x_1x_2} \\ E_{x_2x_1} & E_{x_2x_2} \end{bmatrix}^{-1} E_{x_1y} \]  

(2.5)

Where

\[ C = A'A - A'Z(Z'Z)^{-1}Z'Y \]

\[ Q_{(y)} = A'Y - A'Z(Z'Z)^{-1}Z'Y \]

\[ Q_{(x_1)} = A'X_1 - A'Z(Z'Z)^{-1}Z'X_1 \]

\[ Q_{(x_2)} = A'X_2 - A'Z(Z'Z)^{-1}Z'X_2 \]

\[ E_{x_1x_1} = X_1'X_1 - X_1'Z(Z'Z)^{-1}Z'X_1 - Q_{(x_1)}CQ_{(x_1)} \]

\[ E_{x_1x_2} = X_1'X_2 - X_1'Z(Z'Z)^{-1}Z'X_2 - Q_{(x_1)}CQ_{(x_2)} \]

\[ E_{x_2x_1} = X_2'X_1 - X_2'Z(Z'Z)^{-1}Z'X_1 - Q_{(x_2)}CQ_{(x_1)} \]

\[ E_{x_2x_2} = X_2'X_2 - X_2'Z(Z'Z)^{-1}Z'X_2 - Q_{(x_2)}CQ_{(x_2)} \]

\[ E_{x_1y} = X_1'Y - X_1'Z(Z'Z)^{-1}Z'Y - Q_{(x_1)}CQ_{(y)} \]

\[ E_{x_2y} = X_2'Y - X_2'Z(Z'Z)^{-1}Z'Y - Q_{(x_2)}CQ_{(y)} \]

After substituting these values in (2.2), the error sum of square will be

\[ \text{E. S. S.} = Y'Y - Y'\hat{\pi} - Y'A\hat{t} - Y'X_1\hat{\beta}_1 - Y'X_2\hat{\beta}_2 = E_{yy} - [E_{xy}] [E_{xy}]^{-1} [E_{xy}] \]  

(2.6)

With \((v - 2) \text{ d.f.} \) only.

Under null hypothesis

\[ H_0: t_1 = t_2 = \ldots = t_v = 0 \]

The model (2.1) is reduced to

\[ Y = Z\pi + X_1\beta_1 + X_2\beta_2 + e \]  

(2.7)

The new error sum of square will be

\[ \text{E}_{0,.}\text{S.S.} = \text{min. of } (Y' - Z\pi - X_1\beta_1 - X_2\beta_2)' (Y' - Z\pi - X_1\beta_1 - X_2\beta_2) \]  

(2.8)

with respect to \( \pi, \beta_1, \) and \( \beta_2 \) only. We get the new least square estimates as below:

\[ \pi^* = (Z'Z)^{-1}(Z'Y - X_1'\beta_1 - X_2'\beta_2) \]  

(2.9)

\[ \begin{bmatrix} \beta_1^* \\ \beta_2^* \end{bmatrix} = \begin{bmatrix} E_{x_1x_1}^* & E_{x_1x_2}^* \\ E_{x_2x_1}^* & E_{x_2x_2}^* \end{bmatrix}^{-1} E_{x_1y}^* \]  

(2.10)

Where

\[ E_{x_1x_1}^* = X_1'X_1 - X_1'Z(Z'Z)^{-1}Z'X_1 \]

\[ E_{x_1x_2}^* = X_1'X_2 - X_1'Z(Z'Z)^{-1}Z'X_2 \]

\[ E_{x_2x_1}^* = X_2'X_1 - X_2'Z(Z'Z)^{-1}Z'X_1 \]

\[ E_{x_2x_2}^* = X_2'X_2 - X_2'Z(Z'Z)^{-1}Z'X_2 \]

\[ E_{x_1y}^* = X_1'Y - X_1'Z(Z'Z)^{-1}Z'Y \]

\[ E_{x_2y}^* = X_2'Y - X_2'Z(Z'Z)^{-1}Z'Y \]

After substituting these values in (2.8), the error sum of square will be

\[ \text{E}_{0,.}\text{S.S.} = Y'Y - Y'\pi^* - Y'X_1\beta_1^* - Y'X_2\beta_2^* = E_{yy} - [E_{xy}] [E_{xy}]^{-1} [E_{xy}] \]  

(2.11)
with \((v + v - 3)\) d.f. only.

Treatment sum of square will be obtained by

\[
\text{Treatment S. S.} = E_0.S.S - E.S.S
\]

(2.12)

with \((v - 1)\) d.f. only. The variance covariance matrix will be

\[
V(\hat{t}) = \sigma^2 + M\Phi^{-1}M'\sigma^2
\]

(2.13)

Where

\[
M' = \begin{bmatrix}
\hat{t}_{1(X_1)} & \hat{t}_{2(X_1)} & \cdots & \hat{t}_{v(X_1)} \\
\hat{t}_{1(X_2)} & \hat{t}_{2(X_2)} & \cdots & \hat{t}_{v(X_2)}
\end{bmatrix}
\]

\[
\Phi = \begin{bmatrix}
E_{X_1X_1} & E_{X_1X_2} \\
E_{X_2X_1} & E_{X_2X_2}
\end{bmatrix}
\]

\[
V(\hat{t}_1 - \hat{t}_j) = 2\sigma^2 + [d_1 \quad d_2]\Phi^{-1}[d_1 \quad d_2]^T \sigma^2
\]

(2.14)

Where

\[
d_1 = \{\hat{t}_{i(X_1)} - \hat{t}_{j(X_1)}\} \quad \text{and} \quad d_2 = \{\hat{t}_{i(X_2)} - \hat{t}_{j(X_2)}\}
\]

Average Variance = \(2a\sigma^2 + \frac{2}{(v-1)} \text{tr} M\Phi^{-1}M^T \sigma^2 \) (2.15)

Further discussion on this topic is not relevant to the present study and hence not been presented.

**Section 2**

Without loss of any generality, we may assume that the first \(k\) – treatments have been allotted to the first row and the first \(\lambda\) – treatments and \((k + 1)^{th}, (k + 2)^{th}, \ldots, (2k - \lambda)^{th}\) treatments have been allotted to the second row. Thus, both the rows have first \(\lambda\) treatments in common. We assume that the two missing observations belong to the \((\lambda + 1)^{th}\) treatment in first row, first column and the \((k + 1)^{th}\) treatment in second row and second column respectively. The appropriate model for the analysis of such data is

\[
Y = \mu + A\theta + D\gamma + \beta_2X_1 + \beta_2X_2 + e
\]

(2.16)

with usual notations. The covariate \(X_1\) will assume the value ‘1’ in the first missing cell in first row and ’0’ elsewhere while the covariate \(X_2\) will assume the value ‘1’ in the second missing cell in second row and ’0’ elsewhere. Now using the covariate analysis, the estimates of the missing observations are obtained as below:

\[
\begin{bmatrix}
\hat{Y}_1 \\
\hat{Y}_2
\end{bmatrix} = \begin{bmatrix}
\hat{\beta}_1 \\
\hat{\beta}_2
\end{bmatrix} = -\Phi^{-1} \begin{bmatrix}
E_{X_1Y} \\
E_{X_2Y}
\end{bmatrix} = -\begin{bmatrix}
E_{X_1X_1} & E_{X_1X_2} \\
E_{X_2X_1} & E_{X_2X_2}
\end{bmatrix}^{-1} \begin{bmatrix}
E_{X_1Y} \\
E_{X_2Y}
\end{bmatrix}
\]

Where

\[
\Phi^{-1} = \frac{\lambda k}{k(k-1)(k-2)} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}
\]

(2.17)

And

\[
\begin{bmatrix}
E_{X_1Y} \\
E_{X_2Y}
\end{bmatrix} = -\frac{1}{\lambda k} \begin{bmatrix}
\lambda \nu R_1 + \lambda k C_1 + k(\lambda k_{\lambda+1} - Q_1') - \lambda G \\
\lambda \nu R_2 + \lambda k C_2 + k(\lambda k_{k+1} - Q_2') - \lambda G
\end{bmatrix}
\]

Hence

\[
\begin{bmatrix}
\hat{Y}_1 \\
\hat{Y}_2
\end{bmatrix} = \frac{1}{k(k-1)(k-2)} \begin{bmatrix}
\lambda \nu R_1 + \lambda k C_1 + k(\lambda k_{\lambda+1} - Q_1') - \lambda G \\
\lambda \nu R_2 + \lambda k C_2 + k(\lambda k_{k+1} - Q_2') - \lambda G
\end{bmatrix}
\]

(2.18)

Where \(R_1\) and \(R_2\) are the respective totals of all the known cell observations of first and second row, \(C_1\) and \(C_2\) are the respective totals of all the known cell observations of first and second column, and \(G\) is the total of all the known cell observations in the experiment. \(Q_1\) is the adjusted treatment total of first treatment.

\(Q_1' = Q_1 + Q_2 + \cdots + Q_k\) Total of all the adjusted treatment totals in the first row.

\(Q_2' = Q_1 + Q_2 + \cdots + Q_\lambda + Q_{k+1} + Q_{k+2} + \cdots + Q_{2k-\lambda}\) Total of all the adjusted treatment totals in the second row.

The error sum of square will be

\[
\text{E.S.S.} = (\hat{Y}_1^2 + \hat{Y}_2^2 + \sum \hat{y}_i^2) - \frac{1}{\lambda} \left( (R_1 + \hat{Y}_1)^2 + (R_2 + \hat{Y}_2)^2 + \sum_{j=3}^{b} R_j^2 \right) - \frac{1}{\lambda} \left( (C_1 + \hat{Y}_1)^2 + (C_2 + \hat{Y}_2)^2 + \sum_{i=3}^{c} C_i^2 \right) = \frac{k}{\lambda v} \sum Q_i^2 + \frac{(\hat{Y}_1 + \hat{Y}_2)^2}{\nu r}
\]

(2.19)
with \((v - 1)(k - 2) - 2\) d.f.

Under null hypothesis

\[ H_0: t_1 = t_2 = \cdots = t_v = 0 \]

the model (2.16) is reduced to

\[ Y = E\mu + D\gamma + F\delta + \beta_1X_1 + \beta_2X_2 + e \quad (2.20) \]

and we can obtain the new estimates of the missing observations as below:

\[
\begin{bmatrix}
Y_1^* \\
Y_2^*
\end{bmatrix} = \begin{bmatrix}
\beta_1^* \\
\beta_2^*
\end{bmatrix} = \begin{bmatrix}
E_{X_1}X_1 & E_{X_2}X_2 \\
E_{X_1}X_1 & E_{X_2}X_2
\end{bmatrix}^{-1} \begin{bmatrix}
E_{X_1}Y_1 \\
E_{X_2}Y_2
\end{bmatrix} = \frac{1}{(k - 1)(v - 1)} \begin{bmatrix}
(k - 1)(v - 1) & -1 \\
-1 & (k - 1)(v - 1)
\end{bmatrix} \begin{bmatrix}
Y_1R_1 + kC_1 - G \\
Y_2R_2 + kC_2 - G
\end{bmatrix} (2.21)\]

The error sum of square under the model (2.19) will be

\[
\text{Eo.S.S.} = (Y_1'^2 + Y_2'^2 + \sum \sigma_i^2) - \frac{1}{k} \left( (R_1 + Y_1')^2 + (R_2 + Y_2')^2 + \sum_{f=3}^b \gamma_f^2 \right) - \frac{1}{v} \left( (C_1 + Y_1')^2 + (C_2 + Y_2')^2 + \sum_{f=3}^b \gamma_f^2 \right) + \frac{(g + Y_1'^2 + Y_2'^2)^2}{vK} (2.22)\]

with \((v - 1)(k - 1) - 2\) d.f.

Treatment sum of square will be obtained by

Treatment S. S. = Eo.S.S – E.S.S (2.23)

with \((v) d.f. only. The variance covariance matrix will be

\[
V(\hat{t}) = \frac{2\sigma^2}{\lambda v} I_v + M\Phi^{-1}M'\sigma^2 (2.24)\]

Where

\[
M = \frac{1}{\lambda v} \begin{bmatrix}
-1 & -1 & \cdots & -1 & k - 1 & -1 & 0 & 0 & 0 & \cdots & 0 \\
-1 & -1 & \cdots & -1 & 0 & 0 & 0 & 0 & -1 & \cdots & 0 \\
\cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
0 & 0 & \cdots & 0 & k - 1 & -1 & 0 & -1 & -1 & \cdots & 0 \\
0 & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 & 0 & \cdots & 0
\end{bmatrix} (2.25)\]

The variances of various elementary treatment contrasts are given below:

\[
V(\hat{t}_{u+1} - \hat{t}_u) = V(\hat{t}_{k+1} - \hat{t}_0) = \frac{2\sigma^2}{\lambda v} + \frac{(k^2 + 1)\sigma^2}{\lambda v(k - 1)(k - 2)} (2.26)\]

\[
V(\hat{t}_{h+1} - \hat{t}_h) = V(\hat{t}_{k+1} - \hat{t}_0) = \frac{2\sigma^2}{\lambda v} + \frac{\sigma^2}{\lambda v(k - 1)(k - 2)} (2.27)\]

\[
V(\hat{t}_u - \hat{t}_0) = V(\hat{t}_w - \hat{t}_0) = \frac{2\sigma^2}{\lambda v} + \frac{2\sigma^2}{\lambda v(k - 1)(k - 2)} (2.28)\]

\[
V(\hat{t}_{u+1} - \hat{t}_{k+1}) = \frac{2\sigma^2}{\lambda v} + \frac{2(k - 1)\sigma^2}{\lambda v(k - 2)} (2.29)\]

\[
V(\hat{t}_{h+1} - \hat{t}_h) = \frac{2\sigma^2}{\lambda v} + \frac{(k - 1)\sigma^2}{\lambda v(k - 1)(k - 2)} (2.30)\]

\[
V(\hat{t}_{g+1} - \hat{t}_g) = \frac{2\sigma^2}{\lambda v} + \frac{(k - 1)\sigma^2}{\lambda v(k - 2)} (2.31)\]

\[
V(\hat{t}_{u+1} - \hat{t}_{k+1}) = \frac{2\sigma^2}{\lambda v} + \frac{(k - 1)\sigma^2}{\lambda v(k - 2)} (2.32)\]

\[
V(\hat{t}_{u+1} - \hat{t}_{k+1}) = \frac{2\sigma^2}{\lambda v} + \frac{(k - 1)\sigma^2}{\lambda v(k - 2)} (2.33)\]

\[ u \neq u', w \neq w', g \neq g', h \neq h' \]
This is to be noted that the values of variance of various elementary treatment contrasts get increased when missing observations occur.

\[
\text{Average Variance} = \frac{2k\sigma^2}{Av} + \frac{4k\sigma^2}{Av(v-1)(k-2)} \quad (2.34)
\]

Relative Efficiency \[ V = \frac{(v-1)(k-2)}{(v-1)(k-2)+2} \quad (2.35) \]

Relative Loss in Efficiency \[ 1 - R.E = \frac{2}{(v-1)(k-2)+2} \quad (2.36) \]

Bias \[ B = \frac{(v-1)(k-1)}{vk}\{ (\hat{Y}_1 - Y_1^*)^2 + (\hat{Y}_2 - Y_2^*)^2 \} + \frac{2}{vk}(\hat{Y}_1 - Y_1^*)(\hat{Y}_2 - Y_2^*) \quad (2.37) \]

**Illustration:** Consider the data obtained from a Youden Square Design with parameters \( v = b = 5, r = k = 4, \lambda = 3 \). The two missing observations belong to treatment D in row I and treatment E in row II respectively.

<table>
<thead>
<tr>
<th>Rows</th>
<th>Columns</th>
<th>I</th>
<th>II</th>
<th>III</th>
<th>IV</th>
</tr>
</thead>
<tbody>
<tr>
<td>I</td>
<td>A = 20</td>
<td>B</td>
<td>20</td>
<td>C</td>
<td>23</td>
</tr>
<tr>
<td>II</td>
<td>B = 16</td>
<td>A</td>
<td>18</td>
<td>E</td>
<td>–</td>
</tr>
<tr>
<td>III</td>
<td>C = 14</td>
<td>D</td>
<td>19</td>
<td>A</td>
<td>12</td>
</tr>
<tr>
<td>IV</td>
<td>D = 18</td>
<td>E</td>
<td>18</td>
<td>B</td>
<td>15</td>
</tr>
<tr>
<td>V</td>
<td>E = 17</td>
<td>C</td>
<td>16</td>
<td>D</td>
<td>24</td>
</tr>
</tbody>
</table>

The first missing observation from row I is assumed to be ‘\( Y_1 \)’ and second missing observation from row II as ‘\( Y_2 \)’ respectively. For testing the null hypothesis

\( H_0: \) The treatments are homogeneous

We obtain the estimates of missing observations, corresponding error sum of squares, and treatment sum of squares as below:

By using (2.18), and (2.19), we get

\[ \hat{Y}_1 = 32.6667, \hat{Y}_2 = 25.6667, E.S.S. = 29.74446 \text{ with 6 df only.} \]

By using (2.21), and (2.22), we get

\[ \hat{Y}_1 = 24.1468, \hat{Y}_2 = 21.2378, E_{vP} \text{ S.S.} = 165.27769 \text{ with 10 df only.} \]

By using (2.23), we get

Treatment S. S. = \( E_{vP} \text{ S.S.} - E.S.S. = 135.53323 \text{ with 4 df only.} \)

The learned readers/researchers can construct the ANOVA Table easily.

The variance of various elementary treatment contrasts are obtained as below:

\[ V(\hat{\ell}_A - \hat{\ell}_D) = V(\hat{\ell}_B - \hat{\ell}_D) = V(\hat{\ell}_C - \hat{\ell}_D) = V(\hat{\ell}_A - \hat{\ell}_E) = V(\hat{\ell}_B - \hat{\ell}_E) = V(\hat{\ell}_C - \hat{\ell}_E) = = \frac{8\sigma^2}{15} + \frac{17\sigma^2}{90} \]

\[ V(\hat{\ell}_A - \hat{\ell}_B) = V(\hat{\ell}_A - \hat{\ell}_C) = V(\hat{\ell}_B - \hat{\ell}_C) = \frac{8\sigma^2}{15} \]

\[ V(\hat{\ell}_D - \hat{\ell}_E) = \frac{8\sigma^2}{15} + \frac{\sigma^2}{5} \]

Average Variance = \[ \frac{8\sigma^2}{15} + \frac{2\sigma^2}{15} \]

Relative Efficiency = \[ \frac{4}{5} \]

Relative Loss in Efficiency = \[ \frac{1}{5} \]

3. **References**


14. Kaushik AK, Shiv Kumar, Case of two missing observations in Youden square design belonging to different rows, same column, and different treatments (Both are not common in both the rows), Int. J of Stat and Appl. Maths. 2019; 4(5):25-30.