# International Journal of Statistics and Applied Mathematics 

## ISSN: 2456-1452

Maths 2023; 8(2): 94-100
© 2023 Stats \& Maths https://www.mathsjournal.com
Received: 14-01-2023
Accepted: 16-02-2023

## AI EL-Deosokey

Higher Future Institute for Specialized Technological Studies, Egypt

AM Ben Aros
Department of Statistics, Faculty of Science, Almergib
University, Libya

## MA Ghazal

Department of Mathematics, Faculty of Science, University of Damietta, Egypt

# Linearly immutable continuously time series modeled bivariate stochastic processes with vector values: Distinguishing features 

AI EL-Deosokey, AM Ben Aros and MA Ghazal

DOI: https://doi.org/10.22271/maths.2023.v8.i2b. 958


#### Abstract

Certain observations are assumed to be missed while studying finite continual extended Fourier transformations of time series with precisely stable $(\mathrm{i}+\mathrm{j})$ vector values. This is assumed to be the case. This is because the procedure requires studying extended finite Fourier transforms in a standardized manner. The goal is to get as close to an exact interpretation of the results as possible with the data at hand. The results will be put to use in decision-making, which is why this is being done. As a result of this new data, the continuously Fourier transformation will take a starring role in the findings. Asymptotic moments are currently receiving a lot of consideration from researchers all over the world. Case studies on the topic of electrical energy will be used to test our theoretical concepts.


Keywords: Autocovariance, continuously fixed time process, power spectrum, spectrum density, tapered data

## 1. Introduction

We examine the statistical properties of the linearity relationship between $\mathrm{X}(\mathrm{t})$ and $\mathrm{Y}(\mathrm{t})$ as represented by the extended finite Fourier transformation, following proposals by D.R. Brillinger (1967) ${ }^{[3]}$, M. Rosenblatt, (1967) ${ }^{[3]}$; D.R. Brillinger (2001) ${ }^{[4]}$, Ghazal and Farag (2005) ${ }^{[8]}$, Teamah (2004) ${ }^{[1]}$ and Elhassain (2014) ${ }^{[2]}$ and Ghazal, et al. (2005) ${ }^{[8]}$; For a brief overview, of the format of the article, consider the following: (Part1) is an introductory section., Part (2) explored the Approximate Attributes of process as observed, investigated the Approximating aspects of the process as unobserved in Part (3), and in Part (4) we implement our theoretic ideas into practical application, Our method was applied to a study of Average monthly energy imports and exports of the General Electric Corporation between January 2011 and December 2020.

## 2. The Observed Process's Approximate Attributes

Presume of a fixed sequence that is a vector of values $(i+j)$
$\mathfrak{R}(t)=\left[\begin{array}{ll}X(t) & Y(t)\end{array}\right]^{T}$
$t=0, \pm 1, \pm 2, \ldots, X(t)$ i- valued-vector and $Y(t) \mathrm{j}$ - valued-vector. In a definition of the mean function, we suppose that the process (2.1) is a fixed $(i+j)$ valued- vector sequence with parameters $\left[\begin{array}{ll}X_{r}(t) & Y s(t)\end{array}\right]^{T}, r=1,2, \ldots, j, s=1,2, . ., i$ and that its moments is valid, thus we may deduce the mean function as follow.
$E X(t)=0, E Y(t)=0$
With covariance
$E\left\{\left[X(t+g)-\tau_{x}\right]\left[X(t)-\tau_{x}\right]^{T}\right\}=\tau_{x x}(g)$
$E\left\{\left[X(t+g)-\tau_{x}\right]\left[Y(t)-\tau_{y}\right]^{T}\right\}=\tau_{x y}(g)$
$E\left\{\left[Y(t+g)-\tau_{y}\right]\left[Y(t)-\tau_{y}\right]^{T}\right\}=\tau_{y y}(g)$

Corresponding Author:
AI EL-Deosokey
Higher Future Institute for Specialized Technological Studies, Egypt

With density spectrums
$f_{x x}(h)=\int_{-\infty}^{\infty} 1 /(2 \pi)^{\sum_{g=-\infty}^{\infty} \tau_{x x}(g) \operatorname{Exp}(-i h g)}$
$f_{x y}(h)=\int_{-\infty}^{\infty} 1 /(2 \pi)^{\sum_{g=-\infty}^{\infty} \tau_{x y}(g) \operatorname{Exp}(-i h g)}$
$f_{y y}(h)=\int_{-\infty}^{\infty} 1 /{ }_{(2 \pi)} g \sum_{u=-\infty}^{\infty} \tau_{y y}(g) \operatorname{Exp}(-i h g)$, for $-\infty<h<\infty$
That $\beta_{a}(t), a=1,2, \ldots, i,(t \in R)$ exists for all $t$, which is independent on
$\Re(t) P\left[\beta_{a}(t)=1\right]=p_{a}, P\left[\beta_{a}(t)=0\right]=q_{a}$,
Take note that
$E\left\{\beta_{a}(t)\right\}=P$,
Independent data can be used successfully without caring about the results of another. For the modified series perception, considering
$\delta(t)=\beta(t) \Re(t)$,
Where
$\delta_{a}(t)=\beta_{a}(t) \Re_{a}(t)$,
and
$\beta_{a}(t)=\left\{\begin{array}{l}1, \text { if } X_{a}(t), Y_{a}(t) \text { are recorded } \\ 0, \text { otherwise }\end{array}\right.$,

## Assumption

The time interval ( t ) is limited in the data window $\ell_{a}^{(T)}(t)$ so that it has a restricted range, a finite variation, and vanishes between 0 and $T-1$. Let
$T^{-1} \int_{0}^{T} \ell_{a}^{(T)}(t) d t \underset{T \rightarrow \infty}{\longrightarrow} \int_{0}^{1} \ell_{a}(g) d g, \quad a=\overline{1, i}$
$\gamma_{a_{1}, \ldots, a_{k}}^{(T)}(h)=\int_{0}^{T}\left[\prod_{r=1}^{N} \ell_{a r}^{(T)}(t)\right] \exp \{-i h t\} d t$

## 3. Approximating Aspects of the Unobserved Procedure

## Theorem 3.1. [7]

If we assume that the fixed stochastic procedure is represented by $X_{a}(t), Y_{a}(t), a=1,2, \ldots, \min (i, j)$, that missing data points are represented by $\delta_{a}(t)=\beta_{a}(t) \Re_{a}(t), a=1,2, \ldots \min (i, j)$, We obtain the following if $\beta_{a}(t)$ is a Bernoulli sequence of stochastic process that satisfies (2.8) and (2.9).
$E\left\{\delta_{a}(t)\right\}=0$,
$\operatorname{Cov}\left\{\delta_{a_{1}}\left(t_{1}\right), \delta_{a_{2}}\left(t_{2}\right)\right\}=P_{a_{1} a_{2}}\left[\begin{array}{cc}\tau_{x x}(g) & \tau_{x x}(g) K(h)^{T} \\ K(h) \tau_{x x}(g) & K(h) \tau_{x x}(g) K(h)^{T}\end{array}\right]$,

## Lemma 3.1.

Specifically, if we set $\omega_{a}^{(T)}(h), a=1, \ldots, \min (j, i)$ similar to
$\omega_{a}^{(T)}(h)=\left[2 \pi \int_{0}^{T}\left(\ell_{a}^{(T)}(t)\right)^{2}\right]^{-1 / 2} \int_{-\infty}^{\infty} \ell_{a}^{(T)}(t) \delta_{a}(t) \exp \{-i h t\} d t$, forh $\in R$
Then the dispersion of $\omega_{a}^{(T)}(h)$ is thus determined to be as follows:

$$
\begin{gather*}
D \omega_{a}^{(T)}(h)= \\
P_{a a} \times\left[\begin{array}{cc}
\int_{-\infty}^{\infty} f_{a a}(h-\psi) \times \zeta_{a a}(\psi) d \psi & \int_{-\infty}^{\infty} f_{a a}(h-\psi) K(h)^{T} \times \zeta_{a a}(\psi) d \psi \\
\int_{-\infty}^{\infty} K(h) f_{a a}(h-\psi) \times \zeta_{a a}(\psi) d \psi & \int_{-\infty}^{\infty} K(h) f_{a a}(h-\psi) K(h)^{T} \times \zeta_{a a}(\psi) d \psi
\end{array}\right] \tag{3.4}
\end{gather*}
$$

Where

$$
\begin{array}{r}
\zeta_{a a}{ }^{(T)}(x)=\left[\int_{0}^{T}(2 \pi)\left(\ell_{a}^{(T)}(t) d t\right]^{-1}\left|\partial_{a}^{(T)}(x)\right|,\right. \\
\partial_{a}^{(T)}(x)=\int_{0}^{T} \ell_{a}^{(T)}(t) \exp (-i x t) d t, x \in R
\end{array}
$$

## Proof.

Using equation (3.3) we have

$$
D \omega_{a}^{(T)}(h)=
$$

$=p_{a_{1} a_{2}}\left[\begin{array}{cc}\int_{-\infty}^{\infty} f_{a_{1} a_{2}}(u) \times \zeta_{a_{1} a_{2}}\left(h_{1}-u, h_{2}-u\right) d u & \int_{-\infty}^{\infty} f_{a_{1} a_{2}}(u) K(h)^{T} \times \zeta_{a_{1} a_{2}}\left(h_{1}-u, h_{2}-u\right) d u \\ \int_{-\infty}^{\infty} K(h) f_{a_{1} a_{2}}(u) \times \zeta_{a_{1} a_{2}}\left(h_{1}-u, h_{2}-u\right) d u & \int_{-\infty}^{\infty} K(h) f_{a_{1} a_{2}}(u) K(h)^{T} \times \zeta_{a_{1} a_{2}}\left(h_{1}-u, h_{2}-u\right) d u\end{array}\right]$

When $a_{1}=a_{2}=a, a=1,2, \ldots, \min (i, j)$, and $h_{1}=h_{2}=h, h \in R$, via Substitution
$h-u=\psi$, Hence, we get equation (3.4).
Theorem 3.2. If $\zeta_{a a}{ }^{(T)}(x), a=1, \ldots, \min (i, j), x \in R$ is limited and continually function at the point $x=h, h \in R$, then the spectral density function $f_{a a}(x), a=1, \ldots, \min (i, j), x \in R$ is also limited and continuously at this point then.
$\operatorname{Lim}_{T \rightarrow \infty} D \omega_{a}^{(T)}(h)=\left[\begin{array}{l}\left.f_{a a}(h)\right) f_{a a}(h) K(v)^{T} \\ \left.K(v) f_{a a}(h)\right)\end{array} \quad K(v) f_{a a}(h) K(v)^{T}\right] . a=1, \ldots, \min (i, j)$

## Proof

To prove formula (3.5), we have to establish that
$\operatorname{Lim}_{T \rightarrow \infty}\left|D \omega_{a}^{(T)}(h)-p_{a a}\left[\begin{array}{l}\left.f_{a a}(h)\right) f_{a a}(h) K(v)^{T} \\ \left.K(v) f_{a a}(h)\right)\end{array} \quad K(v) f_{a a}(h) K(v)^{T}\right]\right|=0$,
Lemma (3.1) provides the following.
$\left|D \omega_{a}{ }^{(T)}(h)-p_{a a}\left[\begin{array}{lr}\left.f_{a a}(h)\right) & f_{a a}(h) K(v)^{T} \\ \left.K(v) f_{a a}(h)\right) & K(v) f_{a a}(h) K(v)^{T}\end{array}\right]\right| \leq$
$\leq p_{a a}\left[\begin{array}{l}\int_{-\infty}^{\infty}\left|f_{a u}(h-\psi)\right| \\ \int_{-\infty}^{\infty}\left|K(v) f_{a a}(h-\psi)\right|\end{array}\right.$ $\left.\begin{array}{l}\int_{-\infty}^{\infty}\left|f_{a u}(h-\psi) K(v)^{(T)}\right| \\ \int_{-\infty}^{\infty}\left|K(v) f_{a a}(h-\psi) K(v)^{(T)}\right|\end{array}\right]-$
$-\left[\begin{array}{l}\int_{-\infty}^{\infty}\left|f_{a a}(h)\right| \\ \int_{-\infty}^{\infty}\left|K(v) f_{a a}(h)\right|\end{array}\right.$
$\left.\begin{array}{c}\int_{-\infty}^{\infty}\left|f_{a a}(h) K(\nu)^{(T)}\right| \\ \int_{-\infty}^{\infty}\left|K(v) f_{a a}(h-\psi) K(v)^{(T)}\right|\end{array}\right] \eta_{a a}{ }^{(T)}(\psi) d \psi \leq$
$\leq p_{a a}\left[\begin{array}{l}\int_{-\infty}^{\alpha}\left|f_{a u}(h-\psi)\right| \\ \int_{-\infty}^{v}\left|K(v) f_{a a}(h-\psi)\right|\end{array}\right.$
$\left.\begin{array}{l}\int_{-\infty}^{\psi}\left|f_{a u}(h-\psi) K(v)^{(T)}\right| \\ \int_{-\infty}^{w}\left|K(v) f_{a s}(h-\psi) K(v)^{(T)}\right|\end{array}\right]-$
$-p_{a a}\left[\begin{array}{l}\int_{-\infty}^{v}\left|f_{a u}(h)\right| \\ \int_{-\infty}^{v}\left|K(v) f_{a a}(h)\right|\end{array}\right.$
$\left.\begin{array}{c}\int_{-\infty}^{v}\left|f_{a u}(h) K(v)^{(T)}\right| \\ \int_{-\infty}^{v}\left|K(v) f_{a u}(h-\psi) K(v)^{(T)}\right|\end{array}\right] \eta_{a u}{ }^{(T)}(\psi) d \psi+$
$+p_{a a}\left[\begin{array}{ll}\int_{-\psi}^{\psi}\left|f_{a a}(h-\psi)\right| & \int_{-\psi}^{\psi}\left|f_{a a}(h-\psi) k(v)^{T}\right| \\ \int_{-\psi}^{\psi}\left|k(v) f_{a a}(h-\psi)\right| & \int_{-\psi}^{\psi\left|k(v) f_{a a}(h-\psi) k(v)^{T}\right|}\end{array}\right]-$

$$
\begin{aligned}
& -p_{a a}\left[\begin{array}{cc}
\int_{-\psi}^{\prime}\left|f_{a a}(h)\right| & f^{\psi} \\
-\psi^{\prime} & f_{a a}(h) K(v)^{(T)} \mid \\
\int_{-\psi}^{\psi}\left|K(v) f_{a a}(h)\right| & \int^{\psi}\left|K(v) f_{a a}(h-\psi) K(v)^{(T)}\right|
\end{array}{ }^{\eta} a a^{(T)}(\psi) d \psi+\right. \\
& -p_{a a}\left[\begin{array}{lc}
\int_{\psi}^{\infty}\left|f_{a a}(h-\psi)\right| & \int_{\psi}^{\infty}\left|f_{a u}(h-\psi) k(v)^{T}\right| \\
\int_{\psi}^{\infty}\left|k(v) f_{a a}(h-\psi)\right| & \int_{\psi}^{\infty}\left|k(v) f_{a a}(h-\psi) k(v)^{T}\right|
\end{array}\right]- \\
& -p_{a a}\left[\begin{array}{cc}
\int_{v}^{\infty}\left|f_{a a}(h)\right| & \int_{\psi}^{\infty}\left|f_{a a}(h) K(v)^{(T)}\right| \\
\int_{v}^{\infty}\left|K(v) f_{a a}(h)\right| & \int_{\psi}^{\infty}\left|K(v) f_{a a}(h-\psi) K(v)^{(T)}\right|
\end{array} \eta_{a a}^{(T)}(\psi) d \psi\right.
\end{aligned}
$$

$B_{1}+B_{2}+B_{3}$
We'll clarify each one. In particular, we obtain since $f_{a b}(\psi)$ is continuoue at $\Psi=h, a, b=1, . ., \min (i, j)$, then we have
$\mathrm{B}_{2}=p_{a a}\left[\begin{array}{lc}\int_{-\psi}^{*}\left|f_{a a}(h-\psi)\right| & \int_{-\psi}^{\psi}\left|f_{a a}(h-\psi) k(v)^{T}\right| \\ \int_{-\psi}^{\psi \mid}\left|k(v) f_{a a}(h-\psi)\right| & \int_{-\psi}^{\psi}\left|k(v) f_{a a}(h-\psi) k(v)^{T}\right|\end{array}\right]-$
$-p_{a a}\left[\begin{array}{ll}\int_{-\psi}^{\psi}\left|f_{a a}(h)\right| & \int_{-\psi}^{\psi}\left|f_{a s}(h) K(v)^{(T)}\right| \\ \int_{-\psi}^{\psi}\left|K(v) f_{a a}(h)\right| & \int_{-\psi}^{v}\left|K(v) f_{a a}(h-\psi) K(\nu)^{(T)}\right|\end{array}\right] \eta_{a a}{ }^{(T)}(\psi) d \psi+$
$=p_{a a}\left[\begin{array}{l}\int_{-\psi}^{\nu}\left|f_{a a}(h-\psi)-f_{a a}(h)\right| \\ \int_{-\psi}^{v}\left|k(v) f_{a a}(h-\psi)-f_{a a}(h) k(v)\right|\end{array}\right.$

$$
\left.\begin{array}{c}
\int_{-\psi}^{v}\left|f_{a a}(h-\psi) k(v)^{T}-f_{a a}(h) k(v)^{T}\right| \\
\left|k(v) f_{a a}(h-\psi) k(v)^{T}-k(v) f_{a a}(h) k(v)^{T}\right|
\end{array}\right]
$$

$B_{2} \leq \Omega \int_{-\psi}^{\psi} \eta_{a a}{ }^{(T)}(\psi) d \psi \leq \Omega \int_{-\infty}^{\infty} \eta_{a a}(\psi) d \psi \eta_{a a}{ }^{(T)}(\psi) d \psi$
Assuming that $f_{a b}(\psi)$ is continuing at $\psi=h, a, b=1, . ., \min (i, j)$, we've got
$B_{2} \leq \Omega$. Now, $B_{2}$ is very small, so any $\Omega$ very small, so $B_{2}=0$. With a constant G that limits the value of $f_{a a}(h), a=$ $1, \ldots, \min (i, j), h \in R$ to be limited, we have
$B_{1} \leq 2 G \int_{-\infty}^{-\psi} \eta_{a a}^{(T)}(\psi) d \psi \underset{T \rightarrow \infty}{\rightarrow} 0$,
In a similar manner, $B_{3} \underset{T \rightarrow \infty}{\rightarrow} 0$. Therefore
$\left|D \omega_{a}{ }^{(T)}(h)-p_{a a}\left[\begin{array}{l}\left.f_{a a}(h)\right) f_{a a}(h) K(v)^{T} \\ \left.K(v) f_{a a}(h)\right) \\ K(v) f_{a a}(h) K(v)^{T}\end{array}\right]\right| \underset{T \rightarrow \infty}{\rightarrow} 0$
The theorem has been proved, then.

## 4. Practical Study

### 4.1 Energy Import/Export Investigation

From January 2011 to December 2020, this analysis gives a monthly average of the Energy exported by General Electric Company and the Energy imported by the company.

### 4.1.1 Energy Import Analytics

We will compare the results we get using our model of time process with missed values to the results from the standard procedure, when all values are recorded.
Assuming the data $X_{a}(t),(t=(1,2, \ldots, T]$, which is the average monthly Energy that is imported, where all data of the series are recorded, and recorded with some missed, we can write the findings as $\zeta_{a}(t)=\beta_{a}(t) X_{a}(t), a=1,2, \ldots, i$, such that $X_{a}(t),(t=$ $0, \pm 1, \ldots$.$) is a fixed i-valued-vector process. Table (1) compares Findings for the normal Scenario \beta=1, \zeta_{a}(t)=X_{a}(t)$ and that results when some values are missed at random $(\beta=0$.)

Table 1: Investigation of Imported Energy Findings both with and without missed data


### 4.1.2 Analytical Exported of Energy

In this study, we will compare the results produced using the standard methods, in which all data is observed, with those obtained using a fixed-time process model with partial missed of data.
With a fixed j - valued-vector time process, $Y_{a}(t),\left(t=(1,2, \ldots, T]\right.$ and a stochastically independent Bernoulli sequence, $\beta_{a}(t)$, the results can be written as $\varpi_{a}(t)=\beta_{a}(t) Y_{a}(t), a=1,2, \ldots, j$, an average monthly energy exports with complete records is denoted by $Y_{a}(t)$, where $a=1,2, \ldots, j$. Table 2 compares the results for the two scenarios where some data are missing at random $(\beta=0)$ and results for the standard case $(\beta=0)$.

Table 2: Analyzing the Differences between Outcomes for Exported Energy with and Without Missed Data


### 4.1.3 Regression Model Analysis of Energy Imports and Exports

In this analysis, we will evaluate the two scenarios listed in the table below using our outcomes from monthly averages of energy imports and exports are analyzed using a regression model where the outcomes from model with some missed of observations and the classical results from the same model when all observations are available is shown through table (3).

Table 3: Missing Data in Regression Analysis: A Comparison to Complete Data


### 4.1.4 Conclusion

1. The findings of missing data time process analysis were identical to those obtained from regular time series analysis.
2. As with missed data, the results of the investigated for both the $\mathrm{X}(\mathrm{t})$ and $\mathrm{Y}(\mathrm{t})$ regression models are equivalent since they met the analytical, numerical, and least squares constraints for a regression model between standard time series.

## 5. References

1. Teamah AAM, Bakouch HS. Multivariate Spectral Estimators Time Series with Distorted Observations, International Journal of Pure and Applied Mathematics. 2004;1(1):45-57.
2. Elhassain A. On the Theory of continuous Time series, Indian Journal of Pure and Applied Mathematics. 2014;45(3):297-310.
3. Brillinger DR, Rosenblatt M. Approximated theory of estimates of k-th order spectra, in: B. Harris (Ed.), Advanced Seminar on Spectral Analysis of time series, Wiley, New York; c1967. p. 153-188.
4. Brillinger DR. Time Series Data Analysis and Theory; c2001.
5. Mokaddis GS, Ghazal MA, El-Desokey E. Approximated properties of Spectral Estimates of Second-Order with

Missing Observations, Journal of Mathematics and statistics. 2010;6(1):10-16.
6. Ghazal MA. On a spectral density estimate on noncrossed intervals observation, International Journal of Applied Mathematics. 1999;1(8):875-882.
7. Ghazal MA, Eldesokey AI, Ben Aros AM. Periodogram Analysis with missed observation between two vector valued stochastic process, International Journal of Advanced Research. 2017;5(11):336-349.
8. Ghazal MA, Farag EA, EL-Desokey AE. Some properties of the Discrete Expanded finite Fourier transform with missing Observations. 2005;40(3-30):887902.
9. Ghazal MA, Mokaddis GS, El-Desokey AE. Spectral analysis of strictly stationary continuous time series. Journal of Mathematical Sciences. 2009;3(1):1-5
10. Dahlhaus R. On a Spectral Density Estimate Obtained by Averaging Power Spectral, Journal of Applied Probability. 1985;22:592-610.

